

System of Equations

1. (a) (4, -2, 2) (b) (1, -1, 2) (c) (0, 1) (d) inconsistent (e) (-2-5t, 2+2t, t), $t \in \mathbb{R}$.

2. **Method 1 (Determinant)**

$$\Delta = 0 \Rightarrow \begin{vmatrix} 1 & 1 & 3 \\ 4 & \beta & -1 \\ 6 & 7 & 5 \end{vmatrix} = 0 \Rightarrow 65 - 13\beta = 0 \Rightarrow \beta = 5$$

$$\Delta_x = 0 \Rightarrow \begin{vmatrix} \alpha & 1 & 3 \\ 1 & 5 & -1 \\ 2 & 7 & 5 \end{vmatrix} = 0 \Rightarrow -16 + 32\alpha = 0 \Rightarrow \alpha = 0.5$$

$$\text{Also, } \Delta_y = \begin{vmatrix} 1 & 0.5 & 3 \\ 4 & 1 & -1 \\ 6 & 2 & 5 \end{vmatrix} = 0, \quad \Delta_z = \begin{vmatrix} 1 & 1 & 0.5 \\ 4 & 5 & 1 \\ 6 & 7 & 2 \end{vmatrix} = 0$$

Since not all cofactors of $\Delta = 0$, the system of equations has infinite number of solutions.

Method 2 (Matrix)

Using augmented matrix:

$$\left(\begin{array}{ccc|c} 1 & 1 & 3 & \alpha \\ 4 & \beta & -1 & 1 \\ 6 & 7 & 5 & 2 \end{array} \right) \sim \left(\begin{array}{ccc|c} 1 & 1 & 3 & \alpha \\ 0 & \beta - 4 & -13 & 1 - 4\alpha \\ 0 & 1 & -13 & 2 - 6\alpha \end{array} \right) \sim \left(\begin{array}{ccc|c} 1 & 1 & 3 & \alpha \\ 0 & 1 & -13 & 2 - 6\alpha \\ 0 & \beta - 4 & -13 & 1 - 4\alpha \end{array} \right) \sim \left(\begin{array}{ccc|c} 1 & 1 & 3 & \alpha \\ 0 & 1 & -13 & 2 - 6\alpha \\ 0 & 0 & 13\beta - 65 & 1 - 4\alpha - (2 - 6\alpha)(\beta - 4) \end{array} \right)$$

In order that the system of equations has infinitely many solutions,

$$\begin{cases} 13\beta - 65 = 0 \\ 1 - 4\alpha - (2 - 6\alpha)(\beta - 4) = 0 \end{cases} \Rightarrow \begin{cases} \beta = 5 \\ \alpha = 0.5 \end{cases}$$

$$3. \begin{cases} (4-\lambda)x + 3y + z = 0 \\ 3x - (4+\lambda)y + 7z = 0 \\ x + 7y - (6+\lambda)z = 0 \end{cases} \text{ has nontrivial solutions} \Rightarrow \Delta = 0 \Rightarrow \begin{vmatrix} 4-\lambda & 3 & 1 \\ 3 & -4-\lambda & 7 \\ 1 & 7 & -6-\lambda \end{vmatrix} = 0$$

$$\Rightarrow \lambda^3 + 6\lambda^2 - 75\lambda = 0 \Rightarrow \lambda(\lambda^2 + 6\lambda - 75) = 0 \Rightarrow \lambda = 0, -3 \pm 2\sqrt{21}$$

Since λ is an integer, therefore $\lambda = 0$

$$\text{The system is then reduced to } \begin{cases} 4x + 3y + z = 0 & \dots(1) \\ 3x - 4y + 7z = 0 & \dots(2) \\ x + 7y - 6z = 0 & \dots(3) \end{cases}$$

Since (1) - (2) \equiv (3), eq. (3) is dependent on (1) and (2) and is redundant.

$$\text{Solving (1) and (2), } \frac{x}{\begin{vmatrix} 3 & 1 \\ -4 & 7 \end{vmatrix}} = \frac{y}{\begin{vmatrix} 1 & 4 \\ 7 & 3 \end{vmatrix}} = \frac{z}{\begin{vmatrix} 4 & 3 \\ 3 & -4 \end{vmatrix}} \Rightarrow \frac{x}{25} = \frac{y}{-25} = \frac{z}{-25} \Rightarrow x = -y = -z$$

\therefore The solution is $(x, y, z) = (t, -t, -t)$, where $t \in \mathbb{R}$.

$$4. (a) \begin{vmatrix} p+1 & 1 & 1 \\ 1 & p+1 & 1 \\ 1 & 1 & p+1 \end{vmatrix} \underset{C_1 \rightarrow C_1 + C_2 + C_3}{=} \begin{vmatrix} p+3 & 1 & 1 \\ p+3 & p+1 & 1 \\ p+3 & 1 & p+1 \end{vmatrix} = (p+3) \begin{vmatrix} 1 & 1 & 1 \\ 1 & p+1 & 1 \\ 1 & 1 & p+1 \end{vmatrix} = (p+3) \begin{vmatrix} 1 & 1 & 1 \\ 0 & p & 0 \\ 0 & 0 & p \end{vmatrix} = p^2(p+3)$$

(b) (i) (E) has a unique solution

$$\Rightarrow \Delta = \begin{vmatrix} p+1 & 1 & 1 \\ 1 & p+1 & 1 \\ 1 & 1 & p+1 \end{vmatrix} = p^2(p+3) \neq 0 \Rightarrow p \neq 0 \text{ or } -3 \Rightarrow p \in \mathbb{R} \setminus \{0, -3\}$$

(ii) When $p = -3$, $\Delta = \Delta_x = \Delta_y = \Delta_z = 0$.

Since not all cofactors of $\Delta = 0$, the system of equations has infinite number of solutions.

$$(E) \text{ becomes } \begin{cases} -2x + y + z = 0 & \dots(1) \\ x - 2y + z = 0 & \dots(2) \\ x + y - 2z = 0 & \dots(3) \end{cases}$$

$$(2) - (1), \quad 3x - 3y = 0 \quad \Rightarrow \quad x = y, \quad (3) - (2), \quad 3y - 3z = 0 \quad \Rightarrow \quad y = z$$

$$\therefore (x, y, z) = (t, t, t), \quad \text{where } t \in \mathbb{R}.$$

When $p = 0$, $\Delta = \Delta_x = \Delta_y = \Delta_z = 0$.

the system of equations is reduced to only one equation $x + y + z = 0$

and it has infinite number of solutions: $(x, y, z) = (t_1, t_2, -t_1 - t_2)$, where $t_1, t_2 \in \mathbb{R}$.

(iii) no. For $p \in \mathbb{R} \setminus \{0, -3\}$, (E) has a unique solution.

For $p = \{0, -3\}$, (E) has infinite number of solutions

$$5. \quad (E) \begin{cases} (a-b-c)x + 2ay + 2az = 0 \\ 2bx + (b-c-a)y + 2b = 0 \\ 2cx + 2cy + (c-a-b)z = 0 \end{cases} \Leftrightarrow (E') \begin{cases} (a-b-c)x + 2ay + 2az = 0 \\ 2bx + (b-c-a)y + 2bz = 0 \\ 2cx + 2cy + (c-a-b)z = 0 \end{cases} \wedge z = 1$$

$\Rightarrow (E')$ has non-trivial solution other than $(x, y, z) = (0, 0, 0)$

$$\Rightarrow \begin{vmatrix} a-b-c & 2a & 2a \\ 2b & b-c-a & 2b \\ 2c & 2c & c-a-b \end{vmatrix} = \begin{vmatrix} a+b+c & a+b+c & a+b+c \\ 2b & b-c-a & 2b \\ 2c & 2c & c-a-b \end{vmatrix} = \begin{vmatrix} a+b+c & 0 & 0 \\ 2b & -(a+b+c) & 0 \\ 2c & 0 & -(a+b+c) \end{vmatrix}$$

$$= (a+b+c)^3 = 0$$

$$\Rightarrow a+b+c = 0 \quad \dots (*)$$

(1) If $a = b = c = 0$, (E) is reduced to $0x + 0y = 0$,

there are infinitely number of solutions: $(x, y) = (t_1, t_2)$, where $t_1, t_2 \in \mathbb{R}$.

(2) If not all $a, b, c = 0$, using (*), (E) is reduced to $x + y + 1 = 0$

there are infinitely number of solutions: $(x, y) = (t, -t - 1)$, where $t \in \mathbb{R}$.

$$6. \quad (a) \quad A^2 - 4A + 11I = \begin{pmatrix} -7 & 8 \\ -16 & 1 \end{pmatrix} - 4 \begin{pmatrix} 1 & 2 \\ -4 & 3 \end{pmatrix} + \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} = \begin{pmatrix} 0 & 0 \\ 0 & 0 \end{pmatrix} = \mathbf{0}$$

$$A^2 = 4A - 11I$$

$$\Rightarrow A^4 = (4A - 11I)^2 = 16A^2 - 88A + 121I = 16(4A - 11I) - 88A + 121I = -24A - 55I$$

$$= -24 \begin{pmatrix} 1 & 2 \\ -4 & 3 \end{pmatrix} - 55 \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} = \begin{pmatrix} -79 & -48 \\ 96 & -127 \end{pmatrix}$$

$$A^2 - 4A + 11I = 0 \quad \Rightarrow \quad A(A - 4I) = -11I \quad \Rightarrow \quad A \left[\frac{1}{11}(4I - A) \right] = I$$

$$\Rightarrow A^{-1} = \frac{1}{11}(4I - A) = \frac{1}{11} \left[4 \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} - \begin{pmatrix} 1 & 2 \\ -4 & 3 \end{pmatrix} \right] = \frac{1}{11} \begin{pmatrix} 3 & -2 \\ 4 & 1 \end{pmatrix}$$

(b) $\begin{cases} x+2y-3=0 \\ -4x+3y+5=0 \end{cases} \Rightarrow \begin{pmatrix} 1 & 2 \\ -4 & 3 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} 3 \\ -5 \end{pmatrix} \Rightarrow \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} 1 & 2 \\ -4 & 3 \end{pmatrix}^{-1} \begin{pmatrix} 3 \\ -5 \end{pmatrix} = \frac{1}{11} \begin{pmatrix} 3 & -2 \\ 4 & 1 \end{pmatrix} \begin{pmatrix} 3 \\ -5 \end{pmatrix} = \frac{1}{11} \begin{pmatrix} 19 \\ 7 \end{pmatrix}$

7. (a) $\begin{pmatrix} x+y=1 \\ (x-y)P=(x-y) \end{pmatrix} \Leftrightarrow \begin{pmatrix} y=1-x \\ (x-y)\begin{pmatrix} a & 1-a \\ 1-b & b \end{pmatrix}=(x-y) \end{pmatrix} \Rightarrow (x-1-x)\begin{pmatrix} a & 1-a \\ 1-b & b \end{pmatrix}=(x-1-x)$
 $\Rightarrow ((a+b-2)x+(1-b)) - [(a+b-2)x+(1-b)] = (0 \ 0)$

Since $a+b \neq 2$, \exists a unique real 1×2 matrix $(x \ y) = \left(\frac{b-1}{a+b-2}, \frac{a-1}{a+b-2} \right)$ satisfying the system.

(b) $P - Q = \begin{pmatrix} a & 1-a \\ 1-b & b \end{pmatrix} - \begin{pmatrix} x & y \\ x & y \end{pmatrix} = \begin{pmatrix} a - \frac{b-1}{a+b-2} & 1-a - \frac{a-1}{a+b-2} \\ 1-b - \frac{b-1}{a+b-2} & b - \frac{a-1}{a+b-2} \end{pmatrix}$

$$= \begin{pmatrix} \frac{a^2 + ab - 2a - b + 1}{a+b-2} & \frac{(1-a)(a+b-1)}{a+b-2} \\ \frac{(1-b)(a+b-1)}{a+b-2} & \frac{ab + b^2 - 2b + a - 1}{a+b-2} \end{pmatrix} = \begin{pmatrix} \frac{(a-1)(a+b-1)}{a+b-2} & \frac{(1-a)(a+b-1)}{a+b-2} \\ \frac{(1-b)(a+b-1)}{a+b-2} & \frac{(b-1)(a+b-1)}{a+b-2} \end{pmatrix}$$

$$= (a+b-1) \begin{pmatrix} \frac{a-1}{a+b-2} & \frac{1-a}{a+b-2} \\ \frac{1-b}{a+b-2} & \frac{b-1}{a+b-2} \end{pmatrix} = (a+b-1) \begin{pmatrix} 1 - \frac{b-1}{a+b-2} & -\frac{a-1}{a+b-2} \\ -\frac{1-b}{a+b-2} & 1 - \frac{b-1}{a+b-2} \end{pmatrix} = (a+b-1) \left[\begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} - \begin{pmatrix} x & y \\ x & y \end{pmatrix} \right]$$

$$\therefore \lambda = a+b-1$$

$P^n - Q = \lambda^n(I - Q)$ can be proved by induction and noting :

1. $(x \ y)P = (x \ y) \Rightarrow \begin{pmatrix} x & y \\ x & y \end{pmatrix} P = \begin{pmatrix} x & y \\ x & y \end{pmatrix} \Rightarrow QP = Q$

2. $P^{n+1} - Q = P^{n+1} - QP = (P^n - Q)P = \lambda^n(I - Q)P = \lambda^n(P - QP) = \lambda^n(P - Q) = \lambda^n \lambda(I - Q) = \lambda^{n+1}(I - Q)$

8. (a) $\Delta = \begin{vmatrix} 0 & a & 1 \\ 2 & 5 & 0 \\ -2 & 1 & b \end{vmatrix} = 12 - 2ab = 2(6 - ab), \quad ab \neq 6 \Rightarrow \Delta \neq 0 \Rightarrow \text{inverse of } A \text{ exists.}$

$$\text{Min}(A) = \begin{pmatrix} 5b & 2b & 12 \\ ab-1 & 2 & 2a \\ -5 & -2 & -2a \end{pmatrix}, \text{Cof}(A) = \begin{pmatrix} 5b & -2b & 12 \\ 1-ab & 2 & -2a \\ -5 & 2 & -2a \end{pmatrix}, \text{Adj}(A) = \begin{pmatrix} 5b & 1-ab & -5 \\ -2b & 2 & 2 \\ 12 & -2a & -2a \end{pmatrix}$$

$$\text{Inverse of } A = \frac{\text{Adj}(A)}{\Delta} = \frac{1}{12-2ab} \begin{pmatrix} 5b & 1-ab & -5 \\ -2b & 2 & 2 \\ 12 & -2a & -2a \end{pmatrix}$$

$$\begin{aligned} \text{(b)} \quad & \begin{cases} ay+z=2 \\ 2x+5y=1 \\ -2x+y+bz=3 \end{cases} \Leftrightarrow \begin{pmatrix} 0 & a & 1 \\ 2 & 5 & 0 \\ -2 & 1 & b \end{pmatrix} \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} 2 \\ 1 \\ 3 \end{pmatrix} \\ & \Leftrightarrow \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} 0 & a & 1 \\ 2 & 5 & 0 \\ -2 & 1 & b \end{pmatrix}^{-1} \begin{pmatrix} 2 \\ 1 \\ 3 \end{pmatrix} = \frac{1}{12-2ab} \begin{pmatrix} 5b & 1-ab & -5 \\ -2b & 2 & 2 \\ 12 & -2a & -2a \end{pmatrix} \begin{pmatrix} 2 \\ 1 \\ 3 \end{pmatrix} = \frac{1}{12-2ab} \begin{pmatrix} 10b-ab-14 \\ 8-4b \\ 24-8a \end{pmatrix} \\ & x = \frac{10-ab-14}{12-2ab}, \quad y = \frac{4-2b}{6-ab}, \quad z = \frac{12-4a}{6-ab} \quad , \quad \text{where } ab \neq 6 . \end{aligned}$$

$$9. \quad \text{The augmented matrix : } \left(\begin{array}{ccc|c} 1 & 1 & 2 & 1 \\ 2 & -1 & -1 & 2 \\ 4 & 1 & 6 & c \end{array} \right) \xrightarrow{\sim} \left(\begin{array}{ccc|c} 1 & 1 & 2 & 1 \\ 0 & -3 & -2 & 0 \\ 0 & -3 & -2 & c-4 \end{array} \right) \xrightarrow{\sim} \left(\begin{array}{ccc|c} 1 & 1 & 2 & 1 \\ 0 & -3 & -2 & 0 \\ 0 & 0 & 0 & c-4 \end{array} \right)$$

Suppose the system is consistent, $c-4=0 \Rightarrow c=4$.

$$\text{When } c=4, \text{ we have } \begin{cases} x+y+2z=1 \\ -3y-2z=0 \end{cases} \Rightarrow (x, y, z) = (1-4t, -2t, 3t) , \text{ where } t \in \mathbb{R} .$$

10. Let Δ_{ijk} be the determinant formed by the i, j, k equations of the given system. ($i, j, k = 1, 2, 3, 4$)

$$\Delta_{123} = \begin{vmatrix} 1 & p & p^2 \\ 1 & q & q^2 \\ 1 & r & r^2 \end{vmatrix} = \begin{vmatrix} 1 & p & p^2 \\ 0 & q-p & q^2-p^2 \\ 0 & r-q & r^2-q^2 \end{vmatrix} = \begin{vmatrix} q-p & q^2-p^2 \\ r-q & r^2-q^2 \end{vmatrix} = (q-p)(r-q) \begin{vmatrix} 1 & q+p \\ 1 & r+q \end{vmatrix} = (p-q)(q-r)(r-p)$$

$$\text{Replacing } p=1, \text{ respectively we get: } \Delta_{234} = \begin{vmatrix} 1 & 1 & 1 \\ 1 & q & q^2 \\ 1 & r & r^2 \end{vmatrix} = (1-q)(q-r)(r-1)$$

$$\text{Similarly, } \Delta_{134} = \begin{vmatrix} 1 & p & p^2 \\ 1 & 1 & 1 \\ 1 & r & r^2 \end{vmatrix} = (p-1)(1-r)(r-p) , \quad \Delta_{124} = \begin{vmatrix} 1 & p & p^2 \\ 1 & q & q^2 \\ 1 & 1 & 1 \end{vmatrix} = (p-q)(q-1)(1-p)$$

The necessary and sufficient conditions that the system has non-trivial solution(s) is

$$\Delta_{123} = \Delta_{234} = \Delta_{134} = \Delta_{124} = 0 \quad \Leftrightarrow p=q=r=1$$

$$11. \quad \text{(a)} \quad \begin{vmatrix} \alpha & 1 & 0 \\ 1 & 0 & \beta \\ 0 & \beta & \alpha \end{vmatrix} = -\alpha - \alpha\beta^2 = -\alpha(\beta^2 + 1), \quad \alpha \neq 0, \beta \neq -1 .$$

$$\text{(b)} \quad AB = \begin{pmatrix} \alpha & 1 & 0 \\ 1 & 0 & \beta \\ 0 & \beta & \alpha \end{pmatrix} \begin{pmatrix} -\beta^2 & -\alpha & \beta \\ -\alpha & \alpha^2 & -\alpha\beta \\ \beta & -\alpha\beta & -1 \end{pmatrix} = \begin{pmatrix} -\alpha\beta^2 - \alpha & 0 & 0 \\ 0 & -\alpha\beta^2 - \alpha & 0 \\ 0 & 0 & -\alpha\beta^2 - \alpha \end{pmatrix} = -\alpha(\beta^2 + 1)I_3$$

$$A^{-1} = \frac{1}{-\alpha(\beta^2 + 1)} B = \frac{1}{-\alpha(\beta^2 + 1)} \begin{pmatrix} -\beta^2 & -\alpha & \beta \\ -\alpha & \alpha^2 & -\alpha\beta \\ \beta & -\alpha\beta & -1 \end{pmatrix} = \frac{1}{\alpha(\beta^2 + 1)} \begin{pmatrix} \beta^2 & \alpha & -\beta \\ \alpha & -\alpha^2 & \alpha\beta \\ -\beta & \alpha\beta & 1 \end{pmatrix}$$

(c) If $\alpha \neq 0, \beta \neq -1,$

$$\begin{cases} \alpha x + y = 1 \\ x + \beta z = 1 \\ \beta y + \alpha z = 1 \\ \alpha x + y - 2z = 1 \end{cases} \Leftrightarrow \begin{pmatrix} \alpha & 1 & 0 \\ 1 & 0 & \beta \\ 0 & \beta & \alpha \\ \alpha & 1 & -2 \end{pmatrix} \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} 1 \\ 1 \\ 1 \\ 1 \end{pmatrix} \Leftrightarrow \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \frac{1}{\alpha(\beta^2+1)} \begin{pmatrix} \beta^2 & \alpha & -\beta \\ \alpha & -\alpha^2 & \alpha\beta \\ -\beta & \alpha\beta & 1 \end{pmatrix} \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} = \frac{1}{\alpha(\beta^2+1)} \begin{pmatrix} \beta^2 + \alpha - \beta \\ \alpha - \alpha^2 + \alpha\beta \\ -\beta + \alpha\beta + 1 \end{pmatrix}$$

By putting the solution of the first three eq. into the fourth, the system of equation has unique solution if

$$\alpha \frac{\beta^2 + \alpha - \beta}{\alpha(\beta^2+1)} + \frac{\alpha - \alpha^2 + \alpha\beta}{\alpha(\beta^2+1)} - 2 \frac{-\beta + \alpha\beta + 1}{\alpha(\beta^2+1)} = 1 \Rightarrow \alpha\beta + 1 = \beta$$

12. (a) $A = \begin{pmatrix} a+1 & 1 & 1 \\ 1 & a+1 & 1 \\ 1 & 1 & a+1 \end{pmatrix}$, $|A| = 3a^2 + a^3 = a^2(a+3)$.

$$\text{Min } A = \begin{pmatrix} 2a+a^2 & a & -a \\ a & 2a+a^2 & a \\ -a & a & 2a+a^2 \end{pmatrix}, \text{Cof } A = \begin{pmatrix} 2a+a^2 & -a & -a \\ -a & 2a+a^2 & -a \\ -a & -a & 2a+a^2 \end{pmatrix}$$

$$\text{Adj } A = \begin{pmatrix} 2a+a^2 & -a & -a \\ -a & 2a+a^2 & -a \\ -a & -a & 2a+a^2 \end{pmatrix}$$

$$\text{Inverse of } A = \frac{\text{Adj } A}{|A|} = \frac{1}{a(a+3)} \begin{pmatrix} a+2 & -1 & -1 \\ -1 & a+2 & -1 \\ -1 & -1 & a+2 \end{pmatrix}, \text{ where } a \neq 0, -3.$$

(b) (i) $\begin{cases} (a+1)x + y + z = 1 \\ x + (a+1)y + z = b \\ x + y + (a+1)z = b^2 \end{cases}$ is equivalent to $\begin{pmatrix} a+1 & 1 & 1 \\ 1 & a+1 & 1 \\ 1 & 1 & a+1 \end{pmatrix} \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} 1 \\ b \\ b^2 \end{pmatrix}$

When $a \neq 0, -3$, inverse of A exists,

$$\begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} a+1 & 1 & 1 \\ 1 & a+1 & 1 \\ 1 & 1 & a+1 \end{pmatrix}^{-1} \begin{pmatrix} 1 \\ b \\ b^2 \end{pmatrix} = \frac{1}{a(a+3)} \begin{pmatrix} a+2 & -1 & -1 \\ -1 & a+2 & -1 \\ -1 & -1 & a+2 \end{pmatrix} \begin{pmatrix} 1 \\ b \\ b^2 \end{pmatrix} = \frac{1}{a(a+3)} \begin{pmatrix} a+2-b-b^2 \\ -1+(a+2)b-b^2 \\ -1-b+(a+2)b^2 \end{pmatrix}$$

$$x = \frac{a+2-b-b^2}{a(a+3)}, \quad y = \frac{-1+(a+2)b-b^2}{a(a+3)}, \quad z = \frac{-1-b+(a+2)b^2}{a(a+3)}$$

(ii) When $a = 0$, the system of equation becomes: $\begin{cases} x + y + z = 1 \\ x + y + z = b \\ x + y + z = b^2 \end{cases}$

When $b = 1$, the system becomes $x + y + z = 1$

and has infinite number of solution: $(x, y, z) = (1 - t_1 - t_2, t_1, t_2)$, where $t_1, t_2 \in \mathbb{R}$.

When $b \neq 1$, the system is inconsistent and has no solution.

(iii) When $a = -3$, the system of equation becomes: $\begin{cases} -2x + y + z = 1 \\ x - 2y + z = b \\ x + y - 2z = b^2 \end{cases}$

Adding the 3 equations, $b^2 + b + 1 = 0$.

Since $\Delta = 1^2 - 4(1)(1) < 0$. The quadratic equation has no real solution.

\therefore The system of equations is inconsistent and has no solution.

13. (a)
$$\begin{vmatrix} 1 & 1 & 1 \\ p & q & r \\ p^2 & q^2 & r^2 \end{vmatrix} = \begin{vmatrix} 1 & 0 & 0 \\ p & q-p & r-p \\ p^2 & q^2-p^2 & r^2-p^2 \end{vmatrix} = (q-p)(r-p) \begin{vmatrix} 1 & 0 & 0 \\ p & 1 & 1 \\ p^2 & q+p & r+p \end{vmatrix}$$

$$= (q-p)(r-p) \begin{vmatrix} 1 & 0 & 0 \\ p & 1 & 0 \\ p^2 & q+p & r-p \end{vmatrix} = (q-p)(r-p)(r-q) = (p-q)(q-r)(r-p)$$

(b)
$$\begin{pmatrix} 1 & 1 & 1 \\ p & q & r \\ p^2 & q^2 & r^2 \end{pmatrix} \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} p \\ pq \\ pqr \end{pmatrix}$$
. By (a), determinant of coeff. matrix $\neq 0$ since p, q and r are all distinct. Therefore there is unique solution. By Crammer's Rule,

$$x = \frac{\begin{vmatrix} p & 1 & 1 \\ pq & q & r \\ pqr & q^2 & r^2 \end{vmatrix}}{(p-q)(q-r)(r-p)} = \frac{\begin{vmatrix} 1 & 1 & 1 \\ pq & q & r \\ qr & q^2 & r^2 \end{vmatrix}}{(p-q)(q-r)(r-p)} = \frac{\begin{vmatrix} 1 & 0 & 0 \\ pq & 0 & r-q \\ qr & q(q-r) & r(r-q) \end{vmatrix}}{(p-q)(q-r)(r-p)} = \frac{pq(q-r)}{(p-q)(r-p)}$$

$$y = \frac{\begin{vmatrix} 1 & p & 1 \\ p & pq & r \\ p^2 & pqr & r^2 \end{vmatrix}}{(p-q)(q-r)(r-p)} = \frac{\begin{vmatrix} 1 & 1 & 1 \\ p & q & r \\ p^2 & qr & r^2 \end{vmatrix}}{(p-q)(q-r)(r-p)} = \frac{\begin{vmatrix} 1 & 0 & 0 \\ p & q-p & r-p \\ p^2 & qr-p^2 & r^2-p^2 \end{vmatrix}}{(p-q)(q-r)(r-p)} = \frac{p(r-p)[(q-p)(p+r)-qr+p^2]}{(p-q)(q-r)(r-p)} = \frac{p(r-p)[pq-pr]}{(p-q)(q-r)(r-p)} = \frac{p^2}{p-q}$$

$$z = \frac{\begin{vmatrix} 1 & 1 & p \\ p & q & pq \\ p^2 & q^2 & pqr \end{vmatrix}}{(p-q)(q-r)(r-p)} = \frac{\begin{vmatrix} 1 & 0 & 0 \\ p & q-p & q-p \\ p^2 & q^2-p^2 & qr-p^2 \end{vmatrix}}{(p-q)(q-r)(r-p)} = \frac{p(q-p) \begin{vmatrix} 1 & 0 & 0 \\ p & 1 & q-p \\ p^2 & q+p & qr-p^2 \end{vmatrix}}{(p-q)(q-r)(r-p)}$$

$$= \frac{pq(p-q)(q-r)}{(p-q)(q-r)(r-p)} = \frac{pq}{r-p}$$

(c) (i) If $p = q \neq r$, using augmented matrix the system of equations becomes

$$\left(\begin{array}{cccc} 1 & 1 & 1 & p \\ p & p & r & p^2 \\ p^2 & p^2 & r^2 & p^2r \end{array} \right) \sim \left(\begin{array}{cccc} 1 & 1 & 1 & p \\ 0 & 0 & r-p & 0 \\ 0 & 0 & r^2-p^2 & p^2(r-p) \end{array} \right) \sim \left(\begin{array}{cccc} 1 & 1 & 1 & p \\ 0 & 0 & 1 & 0 \\ 0 & 0 & r+p & p^2 \end{array} \right) \sim \left(\begin{array}{cccc} 1 & 1 & 1 & p \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & p^2 \end{array} \right)$$

\therefore The system is inconsistent.

(ii) If $p \neq q = r$,
$$\left(\begin{array}{cccc} 1 & 1 & 1 & p \\ p & q & q & pq \\ p^2 & q^2 & q^2 & pq^2 \end{array} \right) \sim \left(\begin{array}{cccc} 1 & 1 & 1 & p \\ p-q & 0 & 0 & 0 \\ p^2-q^2 & 0 & 0 & 0 \end{array} \right) \sim \left(\begin{array}{cccc} 0 & 1 & 1 & p \\ 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right)$$

$\therefore (x, y, z) = (0, p-t, t)$, $t \in \mathbb{R}$.

14. (a) $p \neq 0, 18$ (b) $q = -15$; $(x, y, z) = (t, 2t, 3t + \frac{5}{3})$, where $t \in \mathbb{R}$.

(c) $q = 15$; $(x, y, z) = (t, s, \frac{5-t-4s}{3})$, where $t, s \in \mathbb{R}$.